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Education Information

Doctorate, Georgia Institute of Technology, Aerospace Engineering, United States Of America 1998 - 2003 Undergraduate, Middle East Technical University, Faculty of Engineering, Department of Aerospace Engineering, Turkey 1990 - 1995

Dissertations

Doctorate, Adaptive Limit Detection and Limit Avoidance, Georgia Institute Of Technology, Aerospace Engineering, 2003

Academic Titles / Tasks

Associate Professor, Middle East Technical University, Faculty of Engineering, 2013 - 2017 Assistant Professor, Middle East Technical University, Faculty of Engineering, 2005 - 2013 Lecturer PhD, Georgia Institute of Technology, Aerospace Engineering, 2003 - 2005 Research Assistant, Georgia Institute of Technology, Aerospace Engineering, 1998 - 2003 Research Assistant, Middle East Technical University, Faculty of Engineering, 1995 - 1996

Advising Theses

YAVRUCUK İ., Control allocation for a multi-rotor e-VTOL aircraft using blended-inverse, Postgraduate,

E.AKSOY(Student), 2021

YAVRUCUK İ., Development of a flight envelope protection system for a helicopter in autorotation, Postgraduate,

E.SELİN(Student), 2021

YAVRUCUK İ., Investigation of the star tracker algorithms and kalman filter integration, Postgraduate,

S.SARGIN(Student), 2019

YAVRUCUK İ., Investigation of dynamic wake theory with run-time varying number of dynamic inflow states,

Postgraduate, A.Karakaya (Student), 2019

YAVRUCUK İ., Surrogate model based system identification and control of gas turbine engines, Doctorate,

S.EKİNCİ(Student), 2019

YAVRUCUK İ., Testing of a flight envelope protection system for fly-by-wire aerial vehicles, Postgraduate, B.Efe(Student), 2019

YAVRUCUK İ., Simulator based evaluation of adaptive envelope protection algorithms for active sidestick controllers, Postgraduate, Z.Ünal(Student), 2019

YAVRUCUK İ., Fault tolerant flight control applications for a fixed wing UAV using linear and nonlinear approaches, Postgraduate, B.ERGÖÇMEN(Student), 2019

YAVRUCUK İ., DYNAMIC MODELING, CONTROL AND ADAPTIVE ENVELOPE PROTECTION SYSTEM FOR HORIZONTAL AXIS WIND TURBINES, Doctorate, M.ŞAHİN(Student), 2018

LEBLEBİCİOĞLU M. K., YAVRUCUK İ., Control and guidance of a multi-mode unmanned aerial vehicle for increased versatility, Doctorate, F.ÇAKICI(Student), 2016

YAVRUCUK İ., Comparison of rotor inflow models for flight simulation fidelity, Postgraduate, F.GÜNER(Student), 2016 YAVRUCUK İ., Development of an intelligent model prediction controller for autonomous helicopters, Postgraduate, Ş.ESER(Student), 2016

YAVRUCUK İ., Direct adaptive flight envelope protection, Doctorate, G.GÜRSOY(Student), 2016

YAVRUCUK İ., Dynamic modelling and simulation of a wind turbine, Postgraduate, A.HAZAL(Student), 2015

TEKİNALP O., YAVRUCUK İ., Developing an investment decision methodology for helicopter systems related to technology factor and base price, Postgraduate, G.KARA(Student), 2014

YAVRUCUK İ., Kalman filter based applications for helicopters, Postgraduate, M.OKATAN(Student), 2014

YAVRUCUK İ., A reactionary obstacle avoidance algorithm for autonomous vehicles, Postgraduate, G.YÜCEL(Student), 2012

YAVRUCUK İ., Controller design and simulation for a helicopter during target engagement, Postgraduate, S.AVCIOĞLU(Student), 2011

TEKİNALP O., YAVRUCUK İ., Development of a UAV testbed, Postgraduate, Z.ÇAKIR(Student), 2011

YAVRUCUK İ., Adaptive control of guided missiles, Doctorate, K.TİRYAKİ (Student), 2010

YAVRUCUK İ., Neural network based online estimation of maneuvering steady states and control limits, Postgraduate, $G.G\ddot{U}RSOY(Student)$, 2010

TEKİNALP O., YAVRUCUK İ., Development of control allocation methods for satellite attitude control, Postgraduate, T.ÇİĞDEM(Student), 2010

YAVRUCUK İ., A probabilistic conceptual design and sizing approach for a helicopter, Postgraduate, S.SELVİ(Student), 2010

YAVRUCUK İ., Adaptation of a control system to varying missile configurations, Postgraduate, Ö.EKİNCİ (Student), 2009 TEKİNALP O., YAVRUCUK İ., Multidisciplinary and multiobjective design optimization of an unmanned combat aerial vehicle (UCAV), Postgraduate, N.ÇAVUŞ (Student), 2009

YAVRUCUK İ., Adaptive neural network applications on missile controller design, Postgraduate, S.SAĞIROĞLU(Student), 2009

YAVRUCUK İ., Adaptive controller applications for rotary wing aircraft models of varying simulation fidelity, Postgraduate, O.TARIMCI(Student), 2009

YAVRUCUK İ., Mathematical model development of the anti torque system of a NOTAR helicopter, Postgraduate, H.MURAT(Student), 2008

YAVRUCUK İ., Evaluation and comparison of helicopter simulation models with different fidelities, Postgraduate, D.YILMAZ(Student), 2008

 $YAVRUCUK\ \dot{I}\text{, Design of an autonomous landing control algorithm for a fixed wing UAV, Postgraduate,}$

V.Kargın(Student), 2007

YAVRUCUK İ., Design of an autonomous landing control algorithm for a fixed wing unmanned aerial vehicle (UAV), Postgraduate, V.KARGIN(Student), 2007

Published journal articles indexed by SCI, SSCI, and AHCI

I. Adaptive envelope protection control of wind turbines under varying operational conditions ŞAHİN M., YAVRUCUK İ.

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II. Fast engine model for FMU-less small turbojet engines

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III. Direct Adaptive Limit and Control Margin Estimation with Concurrent Learning Gursoy G., YAVRUCUK İ.

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IV. Concurrent Learning Enabled Adaptive Limit Detection for Active Pilot Cueing Gursoy G., YAVRUCUK İ.

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V. Mathematical Modeling of the NOTAR Antitorque System for Flight Simulation YAVRUCUK İ., Bakir H. M., UZOL O.

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VI. Online Dynamic Trim and Control Limit Estimation

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JOURNAL OF GUIDANCE CONTROL AND DYNAMICS, vol.35, no.5, pp.1647-1656, 2012 (SCI-Expanded)

VII. A Low Cost Flight Simulator Using Virtual Reality Tools

YAVRUCUK İ., Kubali E., Tarimci O.

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VIII. Flight Evaluation of a Reactionary Envelope Protection System for UAVs

Unnikrishnan S., Prasad J. V. R., YAVRUCUK İ.

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IX. Flight Evaluation of Reactionary Envelope Protection System

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X. Panel-Method-Based Path Planning and Collaborative Target Tracking for Swarming Micro Air Vehicles

Uzol O., Yavrucuk İ., Sezer Uzol N.

JOURNAL OF AIRCRAFT, vol.47, no.2, pp.544-550, 2010 (SCI-Expanded)

XI. Envelope Protection for Autonomous Unmanned Aerial Vehicles

YAVRUCUK İ., Prasad J. V. R., Unnikrishnan S.

JOURNAL OF GUIDANCE CONTROL AND DYNAMICS, vol.32, no.1, pp.248-261, 2009 (SCI-Expanded)

Articles Published in Other Journals

I. Adaptive Envelope Protection Control for the below and above Rated Regions of Wind Turbines Sahin M., Yavrucuk İ.

International Journal of Energy and Power Engineering, vol.14, no.10, pp.275-283, 2020 (Peer-Reviewed Journal)

II. Paraşüt-Yük SistemleriDinamik Modellenmesi ve Yol-Takibi

Gürsoy G., YAVRUCUK İ.

Elektrik Elektronik Bilgisayar ve Biomedical Mühendisliği, 2013 (Peer-Reviewed Journal)

Refereed Congress / Symposium Publications in Proceedings

I. Experimental Evaluation of Panel-Method-Based Path Planning for eVTOL in A Scaled Urban Environment

BİLGİN Z., Bronz M., YAVRUCUK İ.

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II. Experimental Evaluation of Robustness of Panel-Method-Based Path Planning for Urban Air Mobility

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III. Control Allocation Strategies for a Hybrid Controlled Missile with NDI Autopilot Biyikli R., Tekin R., YAVRUCUK İ.

13th Asian Control Conference, ASCC 2022, Jeju, South Korea, 4 - 07 May 2022, pp.1782-1787

IV. Rüzgar Türbinleri için Yenilikçi Uyarlanabilir bir Zarf Koruma Sisteminin Geliştirilmesi ve Farklı Rotor Çaplarındaki Türbinler Üzerinde Simülasyon Testleri

ŞAHİN M., YAVRUCUK İ.

6. İzmir Rüzgar Sempozyumu, İzmir, Turkey, 23 September 2021

V. An Algorithm for Wind Turbine Protection under Iced Rotor Blades ŞAHİN M., YAVRUCUK İ.

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VI. Linear model identification for rotorcraft using adaptive learning

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VII. Panel-method-based path planning for eVTOL in urban environment

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VIII. Simulation model fidelity enhancement using corrective force and moment increments: Review of activity performed in NATO-AVT Panel 296

Taghizad A., White M., Cameron N., Padfield G., YAVRUCUK İ., Myrand-Lapierre V., Nadeau-Beaulieu M., Richard S., Tischler M.

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IX. Adaptive Envelope Protection Control for the Below and Above Rated Regions of Wind Turbines, BEST PAPER AWARD

ŞAHİN M., YAVRUCUK İ.

XIV International Conference on Wind Energy Engineering and Applications, Paris, France, 27 - 28 August 2020

X. Active Hybrid Fault Tolerant Flight Control of an UAV under Control Surface Damage Ergocmen B., YAVRUCUK İ.

American Control Conference (ACC), Colorado, United States Of America, 1 - 03 July 2020, pp.4169-4174

XI. Rüzgar Türbini Kanat Yunuslama Açısı Kontrolcüsü Tasarımı Ve Performans Analizi ŞAHİN M., YAVRUCUK İ.

5. İzmir Rüzgar Sempozyumu, İzmir, Turkey, 3 - 05 October 2019

XII. Yatay Eksenli Rüzgâr Türbinleri İçin Gürbüz Tasarım Yöntemi

ALTUĞ YALÇIN A. H., YAVRUCUK İ., UZOL O.

5. İzmir Rüzgar Sempozyumu ve Sergisi, Turkey, 3 - 05 October 2019

XIII. Performance Comparison of two turbine blade pitch controller design methods based on equilibrium and frozen wake assumption,

ŞAHİN M., YAVRUCUK İ.

10th ANKARA INTERNATIONAL AEROSPACE CONFERENCE (AIAC 2019), Ankara, Turkey, 18 - 20 September 2019

XIV. Sensitivity of Load and Power Responses to Blade Chord and Twist Distributionsfor Various Inflow Turbulence Conditions

ALTUĞ YALÇIN A. H., YAVRUCUK İ., UZOL O.

Wind Energy Science Conference WESC 2019, 17 - 20 June 2019

XV. Helicopter parameters estimation from subspace identification by constrained nonlinear optimization

Avcıoğlu S., KUTAY A. T., LEBLEBİCİOĞLU M. K., Özkazanç Y., YAVRUCUK İ.

45th European Rotorcraft Forum 2019, ERF 2019, Warszawa, Poland, 17 - 20 September 2019, vol.2, pp.1001-

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XVI. Rüzgar Türbinlerinin Dinamik Modellenmesinde Belirli Parametrelerin Güç Eğrisi Tahminine Etkilerinin İncelenmesi

SAHİN M., YAVRUCUK İ.

9. Yenilenebilir Enerji Kaynakları Sempozyumu ve Sergisi, Antalya, Turkey, 03 November 2017

XVII. Dynamical Modeling of a Horizontal Axis Wind Turbine System with Precone and Tilt Angles ŞAHİN M., YAVRUCUK İ.

9TH ANKARA INTERNATIONAL AEROSPACE CONFERENCE (AIAC 2017), Ankara, Turkey, 20 - 22 September 2017

XVIII. Değişken Hızlı Rüzgar Türbinlerinin Kısmı ve Tam Yük Bölgeleri için Kontrolcü Tasarımı ŞAHİN M., YAVRUCUK İ.

9. YENİLENEBİLİR ENERJİ KAYNAKLARI SEMPOZYUMU VE SERGİSİ, Antalya, Turkey, 3 - 05 November 2017

XIX. Development of an Intelligent Least Squares Based Linear Controller for Autonomous Helicopters Kubali E., YAVRUCUK İ.

International Conference on Unmanned Aircraft Systems (ICUAS), Virginia, United States Of America, 7 - 10 June 2016, pp.242-251

XX. Development and Testing of a Fuzzy Logic Controller for a Small Turbojet Engine ekinci s., üşenmez s., YAVRUCUK İ., UZOL O.

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XXI. Engine Limit Detection and Avoidance for Helicopters with Multiple Limits YAVRUCUK İ.

Proceedings of AIAA Atmospheric Flight Mechanics Conference, 19 - 22 January 2015

XXII. A Non-Iterative Direct Approach to Adaptive Limit and Control Margin Estimation YAVRUCUK İ.

Proceedings of AIAA Scitech Conference, 5 - 09 January 2015

XXIII. Kalman Filter Based Modification on Helicopter Adaptive Control

YAVRUCUK İ.

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XXIV. APPLICATION OF A FUZZY LOGIC CONTROLLER FOR SPEED CONTROL ON A SMALL-SCALE TURBOJET ENGINE

Usenmez S., Ekinci S., UZOL O., YAVRUCUK İ.

ASME Turbo Expo: Turbine Technical Conference and Exposition, Düsseldorf, Germany, 16 - 20 June 2014

XXV. Helicopter Slung Load Simulations Using Heli-Dyn+

YAVRUCUK İ.

AIAA Modeling ang Simulation Technologies Conference, 13 August 2013 - 16 August 2012

XXVI. Helikopter Simülatörleri için Dinamik Turboşaft Motor Modeli Geliştirilmesi ve Simülatöre Entegrasyonu

UZOL O., YAVRUCUK İ.

USMOS 2013, Turkey, 11 - 12 June 2013

XXVII. Helikopter Otopilotları için Yaklışma Üst Modu Tasarımı ve Simülasyonu YAVRUCUK İ.

UMOS 2013, Turkey, 11 - 12 June 2013

XXVIII. Online Detection and Avoidance of Helicopter TGT Limits

YAVRUCUK İ.

Proceedings of 69th American Helicopter Society Forum, 21 - 23 May 2013

XXIX. "Design of a Waypoint Tracking Control Algorithm for ParachutePayload Systems YAVRUCUK İ.

2013 2nd CEAS Specialist Conference on Guidance, Navigation & Control, 10 April 2013

XXX. Paraşüt-Yük Sistemlerinin Dinamik Modellenmesi ve Nokta Kontrolü YAVRUCUK İ.

SAVTEK Konferansı, Turkey, 20 - 22 June 2012

XXXI. Heli-Dyn+ Kullanılarak Helikopter-Yük Sistemi Simülasyonlarının Gerçeklenmesi

YAVRUCUK İ.

SAVTEK 2012, Turkey, 20 - 22 June 2012

XXXII. Heli-Dyn+ Kullanılarak Helikopter için Kontrolcü Geliştirilmesi

YAVRUCUK İ.

SAVTEK 2012, Turkey, 20 - 22 June 2012

XXXIII. A Strategy Development APproach for a Small General Aviation Helicopter Program

YAVRUCUK İ.

AIAC 2011, Turkey, 14 - 16 September 2011

XXXIV. Limit Margin Prediction For Helicopters Using Long Term Learning Adaptive Neural Networks

YAVRUCUK İ.

European Rotorcraft Forum, 13 - 15 September 2011

XXXV. Fault Tolerant Control of an Over Actuated UAV

TEKİNALP O., YAVRUCUK İ.

AIAAGuidance, Navigation, and Control Conference, 8 - 11 July 2011

XXXVI. Dynamic Inversion Based Control of a Missile with L1 Adaptive Control Augmentation

Kutluay K. T., YAVRUCUK İ.

IEEE International Conference on Control Applications Part of 2010 IEEE Multi-Conference on Systems and Control, Yokohama, Japan, 8 - 10 September 2010, pp.2374-2379

XXXVII. Long Term Learning Adaptive Neural Network Estimator Based Limit Detection

YAVRUCUK İ.

IFAC Adaptation and Learning in Control and Signal Processing (ALCOSP) Conference, Turkey, 26 August - 28 October 2010

XXXVIII. Concurrent Learning Enabled Adaptive Limit Detection for Active Pilot Cueing

YAVRUCUK İ.

AIAA Guidance, Navigation and Control Conference, 2 - 05 August 2010

XXXIX. Insansız Helikopterin Uçuş Kontrol Algoritmalarının Geliştirilmesi için Test Platformu Çalışmaları

YAVRUCUK İ.

SAVTEK 2010, Turkey, 23 - 25 June 2010

XL. Entegre bir Helikopter Dınamık Modelleme, Simülasyon ve Analiz Ortamı

YAVRUCUK İ.

SAVTEK 2010, Turkey, 23 - 25 June 2010

XLI. Mathematical Modeling of the NOTAR Anti-Torque System for Flight Simulation

YAVRUCUK İ., UZOL O.

66th AHS Annual Forum, 11 - 13 May 2010

XLII. Adaptive control augmentation of a missile

Kutluay K. T., Yavrucuk I.

10th IFAC International Workshop on Adaptation and Learning in Control and Signal Processing, ALCOSP 2010, Antalya, Turkey, 26 - 28 August 2010, vol.1, pp.77-82

XLIII. A new helicopter simulation and analysis tool: Helidyn

Yavrucuk I., Tarimci O., Katircioglu M., Kubali E., Yilmaz D.

36th European Rotorcraft Forum, ERF 2010, Paris, France, 7 - 09 September 2010, vol.2, pp.997-1003

XLIV. Cooperation of three UAV's for Aerial Rescue and Aerial Retrieval

ERKMEN A. M., YAVRUCUK İ., cakir z.

ICAST 09, IEEE International Conference on Adaptive Science and Technology, 14 - 16 December 2009

XLV. Helicopter Design for Handling Qualities Enhancement

YAVRUCUK İ.

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XLVI. Flight Control System Design for an Unmanned Air Vehicle

YAVRUCUK İ.

AIAC 2009, 17 - 19 August 2009

XLVII. The SCALAB Virtual Reality Simulator

YAVRUCUK İ.

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XLVIII. Adaptive Neural Network Applications on Missile Controller Design

YAVRUCUK İ.

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XLIX. Development of Complementary Helicopter Handling Qualities Criteria Based on Performance and Vibratory Loads

YAVRUCUK İ.

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L. Helicopter Flight Simulation and Automatic Flight Control System Design

TEKİNALP O., YAVRUCUK İ.

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LI. Helicopter Sizing for the Turkish Market Using Concurrent Engineering Tools

YAVRUCUK İ.

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LII. Flight Control System Design and Integration for a Small UAV Test Bed

TEKİNALP O., YAVRUCUK İ.

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LIII. Simulation and Flight Control of a Tilt Duct UAV

TEKİNALP O., ÜNLÜ T., YAVRUCUK İ.

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LIV. A Low Cost Flight Simulator Using Virtual Reality Tools

YAVRUCUK İ.

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LV. Gimbal Angle Restricted Control Moment Gyroscope Clusters

TEKİNALP O., Elmas T., YAVRUCUK İ.

4th International Conference on Recent Advances in Space Technologies, İstanbul, Turkey, 11 - 13 June 2009, pp.585-590

LVI. A robust design optimization of a mixed-flow compressor impeller

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LVII. Cooperation Control of Three UAVs for Aerial Rescue and Aerial Retrieval

YAVRUCUK İ.

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LVIII. Helikopterler için Sinir Ağı Tabanlı Adaptif Kontrolcü Tasarımında Ağırlık erkezi Modelleme Hatasının Önemi

YAVRUCUK İ.

TOK, Turkey, 13 - 15 November 2008

LIX. Autolanding Strategies for a Fixed Wing UAV in Adverse Atmospheric Conditions

YAVRUCUK İ.

AIAA Guidance, Navigation and Control Conference and Exhibit, Honolulu, Hawaii, 18 - 21 August 2008

LX. Simulation of the Transient Response of a Helicopter Turboshaft Engine to Hot-Gas Ingestion UZOL O., YAVRUCUK İ.

ASME Turbo Expo 2008, 9 - 13 June 2008

LXI. On the Level of Center of Gravity Modeling Error in Neural Network Based Adaptive Controller Design

YAVRUCUK İ.

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LXII. Development of A Flight Dynamics Model For A UH-1H Helicopter Simulator

YAVRUCUK İ.

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LXIII. Development of A Flight Control System For A UAV In Autonomous Landing

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LXIV. "Simulation Evaluation of A Flight Control System for An Autonomous Fullsize Helicopter YAVRUCUK İ.

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LXV. "Sürü Halinde Uçan Mikro Hava Araçları için Akışkanlar Mekaniği Tabanlı Güzergah Belirleme

Yöntemi

UZOL O., YAVRUCUK İ.

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LXVI. A Multi-Purpose Helicopter Technology Demonstrator for Engineering Students

YAVRUCUK İ.

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LXVII. Panel Method-Based Motion Planning for Swarming MAVs with Probabilistic Target Tracking YAVRUCUK İ., UZOL O.

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LXVIII. "Dağıtık Uçuş Sistemlerinin Komuta Kontrol Tasarımı ve Geliştirilmesi için Simulasyon Tabanlı Test Platformu Yazılımı F-SIM

YAVRUCUK İ.

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LXIX. Iki Kisilik Turbin Motorlu Bir Egitim Helikopterinin Konsept Tasarimi 1. Kisim: METUCOPTER

YAVRUCUK İ.

UHUK 2006, Turkey, 21 September - 23 June 2006

LXX. Ulusal Insansiz Muharip Hava Araci (Imha) Ihtiyacinda Etkin Sistem Tasarimi ve Itki Alt Sisteminin Degerlendirilmesi

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SAVTEK 2006, Turkey, 29 - 30 June 2006

LXXII. "Adaptive Neural Network Based Control System Applications for Autonomous UAV

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LXXIII. Application of Software Enabled Control Technologies to a Full-Scale Unmanned Helicopter

YAVRUCUK İ.

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LXXIV. Simulation Based Envelope Protection Systems for Unmanned Rotorcraft

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LXXV. Adaptive Limit Margin Prediction and Control Cueing for Carefree Maneuvering of VTOL Aircraf

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LXXVI. Adaptive Limit Prediction and Avoidance for Rotorcraft

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LXXVII. Carefree Maneuvering using Adaptive Neural Nets

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LXXIX. Limit Detection and Avoidance for Heli UAVs

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LXXX. Reconfigurable Flight Controller for Extreme Maneuvering of Heli-UAVs

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LXXXI. Automatic Limit Detection and Avoidance

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LXXXII. Reconfigurable Flight Control Using RPM Control For Heli-UAVs

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25.European Rotorcraft Forum, 1 - 07 September 1999

LXXXIII. Simulation and Flight Control Integration Using the Open Control Platform for Unmanned Aerial

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LXXXIV. Simulation of reconfigurable Heli-UAV's using main rotor RPM control in failure modes

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LXXXV. Georgia Tech UAV Software Systems

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Metrics

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