Lect. PhD VELİ BAKIRCIOĞLU

Personal Information

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Research Areas

Machine Dynamics, System Dynamics and Control, Mechanisms, Robotics, Mechatronics, Modeling and Simulation of Dynamic Systems, Sensors / Electrooptics Technologies

Academic Titles / Tasks

Lecturer PhD, Middle East Technical University, Presidency Office, Applied Research Center for Robotics & AI Technologies, 2021 - Continues

Articles Published in Other Journals

- I. OPTIMAL PID CONTROLLER DESIGN FOR TRAJECTORY TRACKING OF A DODECAROTOR UAV BASED ON GREY WOLF OPTIMIZER YILDIRIM Ş., ÇABUK N., BAKIRCIOĞLU V. Konya mühendislik bilimleri dergisi (Online), vol.11, no.1, pp.10-20, 2023 (Peer-Reviewed Journal)
 II. A Literature Review on Walking Strategies of Legged Robots Bakircioglu V., Kalyoncu M.
 - JOURNAL OF POLYTECHNIC-POLITEKNIK DERGISI, vol.23, no.4, pp.961-986, 2020 (ESCI)

Refereed Congress / Symposium Publications in Proceedings

I. Experimental Investigation of the Effect of Mass Load on Flight Performance of an Octorotor and Dodecarotor UAV

YILDIRIM Ş., Çabuk N., Bakircioğlu V.

1st International Conference on Innovation in Engineering, ICIE 2021, Guimarães, Portugal, 28 - 30 June 2021, pp.81-89

II. Adaptive neural-network based fuzzy logic (ANFIS) based trajectory controller design for one leg of a quadruped robot

Bakircioğlu V., Arif Şen M., Kalyoncu M.

5th International Conference on Mechatronics and Control Engineering, ICMCE 2016, Venice, Italy, 14 - 17 December 2016, pp.82-85

- III. Performances comparison of the bees algorithm and genetic algorithm for PID controller tuning Arif Şen M., Bakircioğlu V., Kalyoncu M.
 5th International Conference on Mechatronics and Control Engineering, ICMCE 2016, Venice, Italy, 14 - 17 December 2016, pp.126-130
- IV. Optimization of PID controller based on The Bees Algorithm for one leg of a quadruped robot Bakircioglu V., Sen M. A., Kalyoncu M.
 3rd International Conference on Control, Mechatronics and Automation (ICCMA), Barcelona, Spain, 21 - 22 December 2015, vol.42

Metrics

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