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Eğitim Bilgileri

Doktora, Orta Doğu Teknik Üniversitesi, Fen Bilimleri Enstitüsü, Matematik (Dr), Türkiye 1982 - 1988

Yüksek Lisans, Orta Doğu Teknik Üniversitesi, Fen Bilimleri Enstitüsü, Matematik (Dr), Türkiye 1980 - 1982

Lisans, Orta Doğu Teknik Üniversitesi, Mühendislik Fakültesi, Elektrik-Elektronik Mühendisliği Bölümü, Türkiye 1974 - 1979

Yabancı Diller

İngilizce, C1 İleri

Araştırma Alanları

Mühendislik ve Teknoloji

Akademik Unvanlar / Görevler

Prof.Dr., Orta Doğu Teknik Üniversitesi, Mühendislik Fakültesi, Elektrik Ve Elektronik Mühendisliği Bölümü, 1999 - Devam Ediyor

Doç.Dr., Orta Doğu Teknik Üniversitesi, Mühendislik Fakültesi, Elektrik Ve Elektronik Mühendisliği Bölümü, 1993 - 1999

Yrd.Doç.Dr., Orta Doğu Teknik Üniversitesi, Mühendislik Fakültesi, Elektrik Ve Elektronik Mühendisliği Bölümü, 1988 - 1993

Yönetilen Tezler

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LEBLEBİCİOĞLU M. K. , Alçak yörüngeli bir uydu için kalman filtre tabanlı yönelim belirleme ve kontrol algoritmalarının tasarımı, Yüksek Lisans, G.Efendioğlu(Öğrenci), 2019

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LEBLEBİCİOĞLU M. K. , Underwater gliders: Modeling, control and simulation studies, Yüksek Lisans, S.GÖREN(Öğrenci), 2016

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K.ÇAĞLAR(Öğrenci), 2006

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LEBLEBİCİOĞLU M. K. , Silah etkinlik katsayılarının bulanık mantık yöntemi ile tespit edilmesi, Yüksek Lisans, A.ÇAKIR(Öğrenci), 2004

ÖZGEN C., LEBLEBİCİOĞLU M. K. , Model predictive control (MPC) performance for controlling reaction systems, Yüksek Lisans, İ.AŞAR(Öğrenci), 2004

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- LEBLEBİCİOĞLU M. K. , Optimal trajectory tracking guidance of an aircraft with final velocity constraint, Yüksek Lisans, D.ERDOĞMUŞ(Öğrenci), 1999
- LEBLEBİCİOĞLU M. K. , HALICI U, Fractal image compression techniques, Yüksek Lisans, E.GÜRSES(Öğrenci), 1999
- LEBLEBİCİOĞLU M. K. , Model predictive control using neural networks applied to flight control, Yüksek Lisans, S.TARKAN(Öğrenci), 1999
- LEBLEBİCİOĞLU M. K. , Hybrid methods in intelligent control, Yüksek Lisans, T.SERHAT(Öğrenci), 1999
- ÖZGEN C., LEBLEBİCİOĞLU M. K. , Some sliding mode control applications in brushless DC motor and pH systems, Yüksek Lisans, F.KAFFASHİ(Öğrenci), 1999
- LEBLEBİCİOĞLU M. K. , Fuzzy control of brushless DC motors, Yüksek Lisans, Y.SUBAŞI(Öğrenci), 1998
- LEBLEBİCİOĞLU M. K. , Initial alignment techniques for strapdown inertial navigation systems, Yüksek Lisans, T.İNCİ(Öğrenci), 1997
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- LEBLEBİCİOĞLU M. K. , Image compression based on a fractal theory of iterated function systems, Yüksek Lisans, R.H. (Öğrenci), 1995
- LEBLEBİCİOĞLU M. K. , KUZUOĞLU M., A Four parameter atomic decomposition and the related time-frequency distribution, Doktora, A.BULTAN(Öğrenci), 1995
- LEBLEBİCİOĞLU M. K. , Certain time-frequency representations and their applications, Yüksek Lisans, H.ŞİRİN(Öğrenci), 1995
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- LEBLEBİCİOĞLU M. K. , Controllability and observability in infinite dimensional systems, Yüksek Lisans, H.SEMİH(Öğrenci), 1993
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SCI, SSCI ve AHCI İndekslerine Giren Dergilerde Yayınlanan Makaleler

- I. **Energy and Time Optimal Autopilot for Electric Vehicles Performing Ackerman Cornering**
Ahiska K., ÖZGÖREN M. K. , LEBLEBİCİOĞLU M. K.
IEEE TRANSACTIONS ON INTELLIGENT TRANSPORTATION SYSTEMS, 2022 (SCI İndekslerine Giren Dergi)
- II. **Design, Modeling, and Control Allocation of a Heavy-Lift Aerial Vehicle Consisting of Large Fixed Rotors and Small Tiltrotors**
Ozdogan G., LEBLEBİCİOĞLU M. K.
IEEE-ASME TRANSACTIONS ON MECHATRONICS, 2022 (SCI İndekslerine Giren Dergi)
- III. **Determining allowable parametric uncertainty in an uncommon quadrotor model for closed loop stability**
Baskin M., LEBLEBİCİOĞLU M. K.
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- IV. **Energy Optimality in Electric Vehicles Along Uphill-Downhill Roads**
Ahiska K., ÖZGÖREN M. K. , LEBLEBİCİOĞLU M. K.
IEEE TRANSACTIONS ON INTELLIGENT VEHICLES, cilt.6, sa.3, ss.390-405, 2021 (SCI İndekslerine Giren Dergi)
- V. **Online path planning for unmanned aerial vehicles to maximize instantaneous information**
Ergezer H., LEBLEBİCİOĞLU M. K.
INTERNATIONAL JOURNAL OF ADVANCED ROBOTIC SYSTEMS, cilt.18, sa.3, 2021 (SCI İndekslerine Giren Dergi)
- VI. **Combined system identification and robust control of a gimbal platform**
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- VII. **Identification of Physical Helicopter Models Using Subspace Identification**
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- VIII. **Experimental test of vision-based navigation and system identification of an unmanned underwater survey vehicle (SAGA) for the yaw motion**
Kartal S. K. , LEBLEBİCİOĞLU M. K. , Ege E.
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- IX. **Computerized hybrid decision-making system for hormone replacement therapy in menopausal women**
Bacak H. Ö. , LEBLEBİCİOĞLU M. K. , TANAÇAN A., BEKSAÇ M. S.
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- X. **Computerized prediction system for the route of delivery (vaginal birth versus cesarean section)**
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- XI. **Time series classification with feature covariance matrices**
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- XII. **Experimental test of the acoustic-based navigation and system identification of an unmanned underwater survey vehicle (SAGA)**
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