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Refereed Congress / Symposium Publications in Proceedings

- I. **Developing a Motion Controller for Autonomous Agricultural Robot Otonom Tarım Robotu İçin Hareket Planlayıcının Geliştirilmesi**
GÖLBOL F., Olmez H., Hacinecipoglu A., ANKARALI M. M.
28th Signal Processing and Communications Applications Conference, SIU 2020, Gaziantep, Turkey, 5 - 07 October 2020
- II. **Developing a Motion Controller for Autonomous Agricultural Robot**
GÖLBOL F., Olmez H., Hacinecipoglu A., ANKARALI M. M.
28th Signal Processing and Communications Applications Conference (SIU), ELECTR NETWORK, 5 - 07 October 2020
- III. **Lineer Bir Sistemin Eş Zamanlı Sistem Belirleme ve Durum Kestirimi**
Gölbol F., Ankaralı M. M., Saranlı A.
Türkiye Robotbilim Konferansı Programı, İstanbul, Turkey, 12 - 14 April 2018, pp.243-244
- IV. **RG-Trees: Trajectory-Free Feedback Motion Planning Using Sparse Random Reference Governor Trees**
GÖLBOL F., ANKARALI M. M., SARANLI A.
25th IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), Madrid, Spain, 1 - 05 October 2018, pp.6506-6511

Supported Projects

ANKARALI M. M., GÖLBOL F., SIZLAYAN S. Y., Project Supported by Higher Education Institutions, Ritmik Bir Davranışının Sistem Tanımlaması ve Analizi, 2018 - 2019

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