

Kişisel Bilgiler

E-posta: aydan@metu.edu.tr

Yabancı Diller

İngilizce, C1 İleri

Fransızca, C1 İleri

Yönetilen Tezler

- ERKMEN A. M. , Prediction of renal respiratory motion for compensation during percutaneous needle insertion in robot assisted surgery, Yüksek Lisans, M.ÇETİNKAYA(Öğrenci), 2018
- ERKMEN A. M. , Implementation of fractional order controller for stabilized visual tracking system in real military platforms, Yüksek Lisans, M.BAYINDIR(Öğrenci), 2018
- ERKMEN A. M. , Dynamic formation control with heterogeneous mobile robots, Yüksek Lisans, K.ÇİMENCİ(Öğrenci), 2016
- ERKMEN A. M. , ONLINE MINING OF HUMAN DEEP INTENTION BY PROACTIVE ENVIRONMENT CHANGES USING DEEP NEURAL NETWORKS, Yüksek Lisans, N.BAKİ(Öğrenci), 2015
- ERKMEN A. M. , GROWING 3D MAPS FROM 2D SLAM MAPS OBTAINED BY INDOOR SLAM WITH HETEROGENEOUS MOBILE ROBOTS, Yüksek Lisans, B.ÇETİNKAYA(Öğrenci), 2015
- ERKMEN A. M. , Self-reconfigurable modular exoskeleton, Yüksek Lisans, Ç.ALTINTAŞI(Öğrenci), 2014
- ERKMEN A. M. , Reshaping human intentions by autonomous sociable robot moves through intention transients generated by elastic networks considering human emotions, Yüksek Lisans, O.CAN(Öğrenci), 2014
- ERKMEN A. M. , Cascaded proxy-based sliding mode control enhanced with disturbance observer for the stabilization and control of a gun-turret platform, Yüksek Lisans, E.ÇANDIR(Öğrenci), 2014
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- ERKMEN A. M. , GÖKÇAYD., Blind deconvolution techniques in identifying fMRI based brain activation, Yüksek Lisans, H.İCLAL(Öğrenci), 2011
- ERKMEN A. M. , Mechanical properties identification of viscoelastic/hyperelastic materials based on experimental data, Yüksek Lisans, A.TABAKCI(Öğrenci), 2010
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- ERKMEN A. M. , ERKMEN İ., Intelligent stabilization control of turret subsystems under disturbances from unstructured terrain, Yüksek Lisans, Ö.GÜMÜŞAY(Öğrenci), 2006
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- ERKMEN A. M. , ERKMEN İ., User modeling in mobile environment, Yüksek Lisans, E.ALKILIÇGİL(Öğrenci), 2005
- ERKMEN A. M. , ERKMEN İ., Fuzzy actor-critic learning based intelligent controller for high-level motion control of serpentine robots, Yüksek Lisans, E.ONUR(Öğrenci), 2005
- ERKMEN A. M. , ERKMEN İ., Biologically inspired multichannel modelling of human visual perceptual system, Yüksek Lisans, M.APAYDIN(Öğrenci), 2005
- ERKMEN A. M. , 3-D grasping during serpentine motion with a snake-like robot, Yüksek Lisans, B.ATAKAN(Öğrenci), 2005
- ERKMEN A. M. , ERKMEN İ., A recommendation system combining context-awareness and user profiling in mobile environment, Yüksek Lisans, S.ULUCAN(Öğrenci), 2005
- ERKMEN A. M. , ERKMEN İ., Fault tolerant deployment, search and task cooperative control of robot/sensor networks,

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- **Reshaping human intention in Human-Robot Interactions by robot moves A comparative analysis of HMM and OOM methods**
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- **Fluid swarm formation control for hand gesture imitation by ellipse fitting**
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Kaygisiz B. H. , Erkmen A. M. , Erkmen I.
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- **Intelligent analysis of chaos roughness in regularity of walk for a two legged robot**
Kaygisiz B., Erkmen I., Erkmen A.
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- **Exact kalman filtering of respiratory motion**
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- **IMITATION OF HUMAN BODY POSES BY THE FORMATION CONTROL OF A FLUIDIC SWARM**
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- **Momentum Transfer from the Fingers to Object Based on Fluid Dynamics**
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- **Imitation of Hand Postures with Particle Based Fluidics Method**
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- **A Novel Map Merging Methodology for Multi-Robot Systems**
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- **CATCHING CONTINUUM BETWEEN PRESHAPE AND GRASPING BASED ON FLUIDICS**
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- **FROM FETAL BLOOD-FLOW DOPPLER ULTRASOUND IMAGES USING WAVELET TRANSFORMS**

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Atrflar

Toplam Atf Sayısı (WOS):197

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