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Foreign Languages

English, C1 Advanced

French, C1 Advanced

Advising Theses

- ERKMEN A. M. , Prediction of renal respiratory motion for compensation during percutaneous needle insertion in robot assisted surgery, Post Graduate, M.ÇETİNKAYA(Student), 2018
- ERKMEN A. M. , Implementation of fractional order controller for stabilized visual tracking system in real military platforms, Post Graduate, M.BAYINDIR(Student), 2018
- ERKMEN A. M. , Dynamic formation control with heterogeneous mobile robots, Post Graduate, K.ÇİMENÇİ(Student), 2016
- ERKMEN A. M. , ONLINE MINING OF HUMAN DEEP INTENTION BY PROACTIVE ENVIRONMENT CHANGES USING DEEP NEURAL NETWORKS, Post Graduate, N.BAKİ(Student), 2015
- ERKMEN A. M. , GROWING 3D MAPS FROM 2D SLAM MAPS OBTAINED BY INDOOR SLAM WITH HETEROGENEOUS MOBILE ROBOTS, Post Graduate, B.ÇETİNKAYA(Student), 2015
- ERKMEN A. M. , Self- reconfigurable modular exoskeleton, Post Graduate, Ç.ALTINTAŞI(Student), 2014
- ERKMEN A. M. , Reshaping human intentions by autonomous sociable robot moves through intention transients generated by elastic networks considering human emotions, Post Graduate, O.CAN(Student), 2014
- ERKMEN A. M. , Cascaded proxy-based sliding mode control enhanced with disturbance observer for the stabilization and control of a gun-turret platform, Post Graduate, E.ÇANDIR(Student), 2014
- ERKMEN A. M. , Improvisation based on imitating human players by a robotic acoustic musical device ROMI built as a self playing compound acoustic musical robot, Doctorate, K.AYDIN(Student), 2013
- ERKMEN A. M. , GÖKÇAYD., Wavelet based deconvolution techniques in identifying fMRI based brain activation, Post Graduate, E.ADLI(Student), 2011
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- ERKMEN A. M. , Mechanical properties identification of viscoelastic/hyperelastic materials based on experimental data, Post Graduate, A.TABAKCI(Student), 2010
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- ERKMEN A. M. , ERKMEN İ., User modeling in mobile environment, Post Graduate, E.ALKILIÇGİL(Student), 2005
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- ERKMEN A. M. , ERKMEN İ., Biologically inspired multichannel modelling of human visual perceptual system, Post Graduate, M.APAYDIN(Student), 2005
- ERKMEN A. M. , 3-D grasping during serpentine motion with a snake-like robot, Post Graduate, B.ATAKAN(Student), 2005
- ERKMEN A. M. , ERKMEN İ., A recommendation system combining context-awareness and user profiling in mobile environment, Post Graduate, S.ULUCAN(Student), 2005
- ERKMEN A. M. , ERKMEN İ., Fault tolerant deployment, search and task cooperative control of robot/sensor networks,

Post Graduate, B.AKIN(Student), 2005

ERKMEN A. M. , ERKMEN İ., Intelligent methods for dynamic analysis and navigation of autonomous land vehicles, Doctorate, H.BURAK(Student), 2004

ERKMEN A. M. , ERKMEN İ., Reinforcement learning using potential field for role assignment in a multi-robot two-team game, Post Graduate, F.ÖZGÜL(Student), 2004

ERKMEN A. M. , ERKMEN İ., Online critical game flow and dynamic role assignment based on potential fields, Post Graduate, A.AYHAN(Student), 2004

ERKMEN A. M. , Uncertainty modelling and stability analysis for 2-way fuzzy adaptive systems, Doctorate, E.GÜRKAN(Student), 2003

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ERKMEN A. M. , Minimizing uncertainty in rough control boundaries of robot path planning using decay adjustment algorithm (DDA), Post Graduate, U.ZEKİ(Student), 2001

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ERKMEN A. M. , Holonic modelling of robot hands, Post Graduate, M.DURNA(Student), 1999

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ERKMEN A. M. , Vorticity based manipulability and stability criteria for robot hand preshaping, Post Graduate, H.CANBOLAT(Student), 1993

ERKMEN A. M. , Intelligent sensorimotor control of robot hand preshaping, Post Graduate, C.VEYSEL(Student), 1993

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- **Reshaping human intention in Human-Robot Interactions by robot moves A comparative analysis of HMM and OOM methods**
Durdu A., ERKMEN A. M. , Yılmaz A.
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- **Fluid swarm formation control for hand gesture imitation by ellipse fitting**
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- **Prioritized Mobile Robot Exploration Based on Percolation Enhanced Entropy Based Fast SLAM**
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- **Imitation of basic hand preshapes by fluid based method: fluidics formation control**
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- **A computerized diagnostic system for the interpretation of umbilical artery blood flow velocity waveforms**
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- **INTERPRETATION OF DOPPLER BLOOD-FLOW VELOCITY WAVE-FORMS USING NEURAL NETWORKS**
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Refereed Congress / Symposium Publications in Proceedings

- **Exact kalman filtering of respiratory motion**
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- **Elastic Networks in Reshaping Human Intentions by Proactive Social Robot Moves**
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- **IMITATION OF HUMAN BODY POSES BY THE FORMATION CONTROL OF A FLUIDIC SWARM**
Tilki U., ERKMEN İ., ERKMEN A. M.
11th ASME Biennial Conference on Engineering Systems Design and Analysis, (ESDA 2012), Nantes, France, 2 - 04 July 2012, pp.361-370
- **Morphing Estimated Human Intention via Human-Robot Interactions**
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- **Proxy-Based Sliding Mode Stabilization of a Two-Axis Gimbaled Platform**
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- **Improvisation Based on Imitating Human Players by a Robotic Acoustic Musical Device**
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- **Momentum Transfer from the Fingers to Object Based on Fluid Dynamics**
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- **Imitation of Hand Postures with Particle Based Fluidics Method**
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- **A Novel Map Merging Methodology for Multi-Robot Systems**
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- **NEW PRIORITIZED MULTI-ROBOT EXPLORATION STRATEGY BASED ON PERCOLATION MODEL IN UNKNOWN ENVIRONMENTS**
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- **A snake-like robot for variable friction unstructured terrains, pushing aside debris in clearing passages**
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- **Scalable self-deployment of mobile sensor networks: A fluid dynamics approach**
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- **Equivalent linearization of 2-way fuzzy adaptive system under nonparametric uncertainty and inconsistency**

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Supported Projects

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Citations

Total Citations (WOS):198

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