#### Res. Asst. ATAKAN DURMAZ

#### **Personal Information**

Email: atakand@metu.edu.tr

Web: https://avesis.metu.edu.tr/atakand

#### International Researcher IDs

ScholarID: IZEPwQcAAAAJ ORCID: 0000-0002-7573-2412

Publons / Web Of Science ResearcherID: KYQ-0369-2024

ScopusID: 58453627500 Yoksis Researcher ID: 388584

#### **Education Information**

Postgraduate, Middle East Technical University, Faculty Of Engineering, Department Of Electrical And Electronics Engineering, Turkey 2022 - 2024

Undergraduate, Middle East Technical University, Faculty of Engineering, Department of Electrical and Electronics Engineering, Turkey 2017 - 2022

### Foreign Languages

English, C1 Advanced

## **Research Areas**

Control and System Engineering, Robotics and Mechatronics Systems, Electrical and Electronics Engineering, Engineering and Technology

### **Academic Titles / Tasks**

Research Assistant, Middle East Technical University, Faculty of Engineering, Department of Electrical and Electronics Engineering, 2023 - Continues

Student, Middle East Technical University, Faculty of Engineering, Department of Electrical and Electronics Engineering, 2017 - Continues

Expert, Middle East Technical University, Graduate School of Natural and Applied Sciences, Robotik Anabilim Dalı, 2022 - 2023

### Academic and Administrative Experience

Bilimsel Proje Uzmanı, Middle East Technical University, Graduate School of Natural and Applied Sciences, Robotik Anabilim Dalı, 2022 - 2023

A ..... -1 - - D... | L. | L. | J. | | O.| - ... | T. | ..... | -1 -

### Articles Publisnea in Otner Journals

I. Sensörsüz Seri Elastik Tekniği ile Bir Kablo Sürümlü Düzlemsel Mekanizmanın Kontrolü Kunduz İ., Durmaz A., Albayrak Ö., Alp T., Ünal P., Ankaralı M. M. Avrupa Bilim ve Teknoloji Dergisi, no.41, pp.324-330, 2022 (Peer-Reviewed Journal)

## **Books & Book Chapters**

I. Modeling, Simulation, and Control of a "Sensorless" Cable-Driven Robot
Durmaz A., Albayrak Ö., Ünal P., Ankaralı M. M.
in: Cable-Driven Parallel Robots. CableCon 2023. Mechanisms and Machine Science, Stéphane Caro, Andreas
Pott, Tobias Bruckmann, Editor, Springer Nature, London, pp.197-208, 2023

### Refereed Congress / Symposium Publications in Proceedings

I. Modeling, Simulation, and Control of a "Sensorless" Cable-Driven Robot
DURMAZ A., Albayrak Ö., Ünal P., ANKARALI M. M.
6th International Conference on Cable-Driven Parallel Robots, CableCon 2023, Nantes, France, 25 - 28 June 2023, vol.132, pp.197-208

# **Supported Projects**

Ankaralı M. M., Sürer E., TUBITAK Project, Robot Kontrolcülerini Onarmak Için Zamansal Mantık Kullanan Veri Odaklı Bir Yaklaşım, 2022 - 2025

Ankaralı M. M., TUBITAK Project, Feedback Motion Planning of an Unmanned Surface Vehicle via Random Sequential Composition, 2020 - 2022

#### **Metrics**

Publication: 5